Systems of Systems Case study

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Abstract

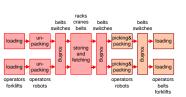
System of Systems case study: a warehouse in a logistics chain.

Distribution

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version: 0



physical partitioning

global goods distribution

super SoS

warehouse

pick and place station

robot

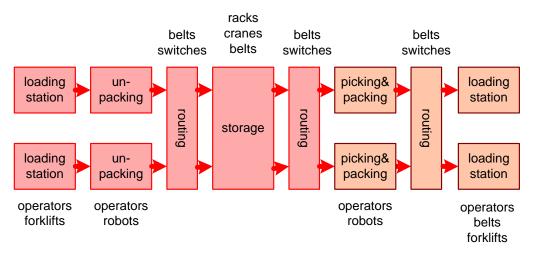
gripper

camera

component

recognizer

functional model

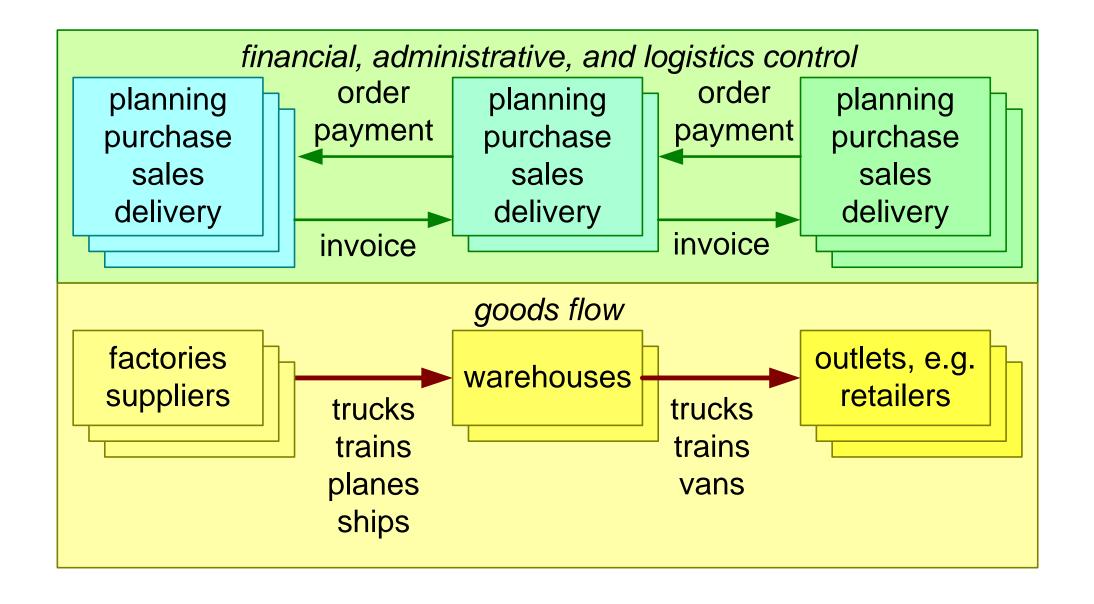


quantification

#items/hour, order size, order variation, delivery time, storage capacity, etc.

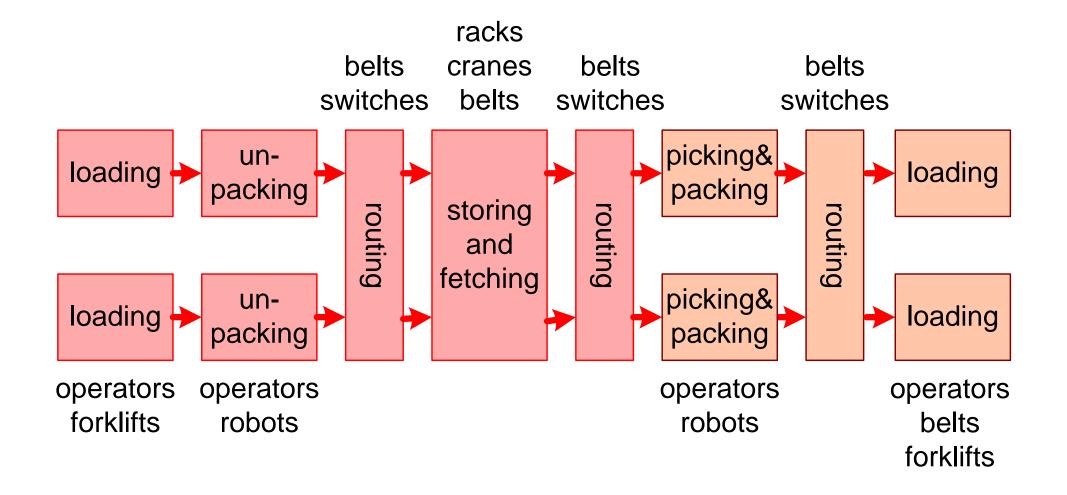
on many levels

Goods and Information Flow



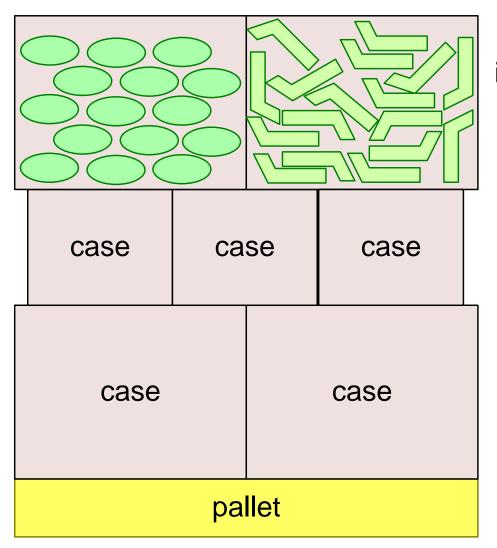


Functional Model Warehouse

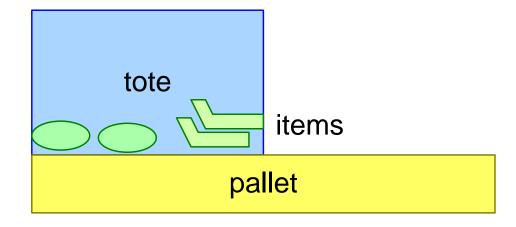




Some Warehouse Jargon

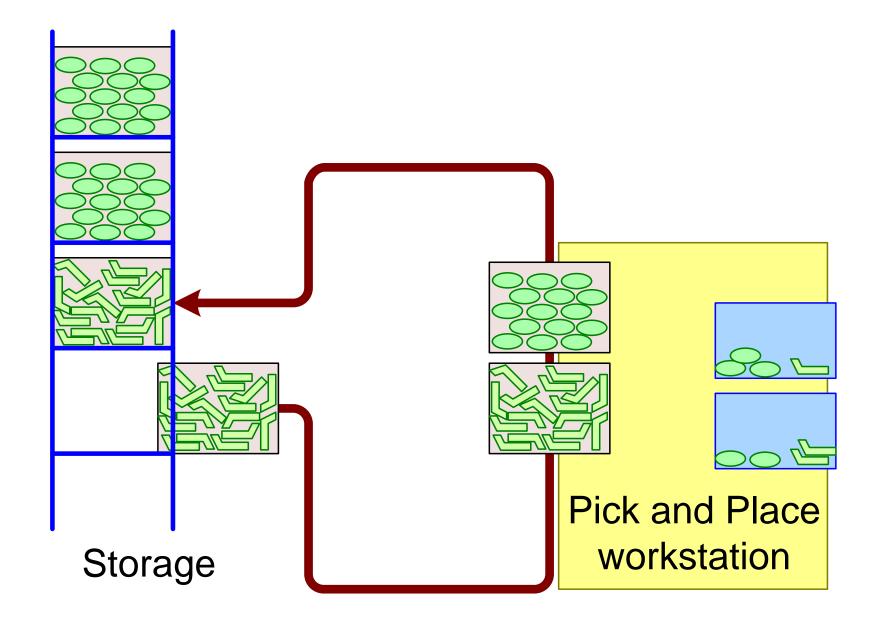


items





Pick and Place





Pick and Place Design Questions

One order at a time?

One item at a time?

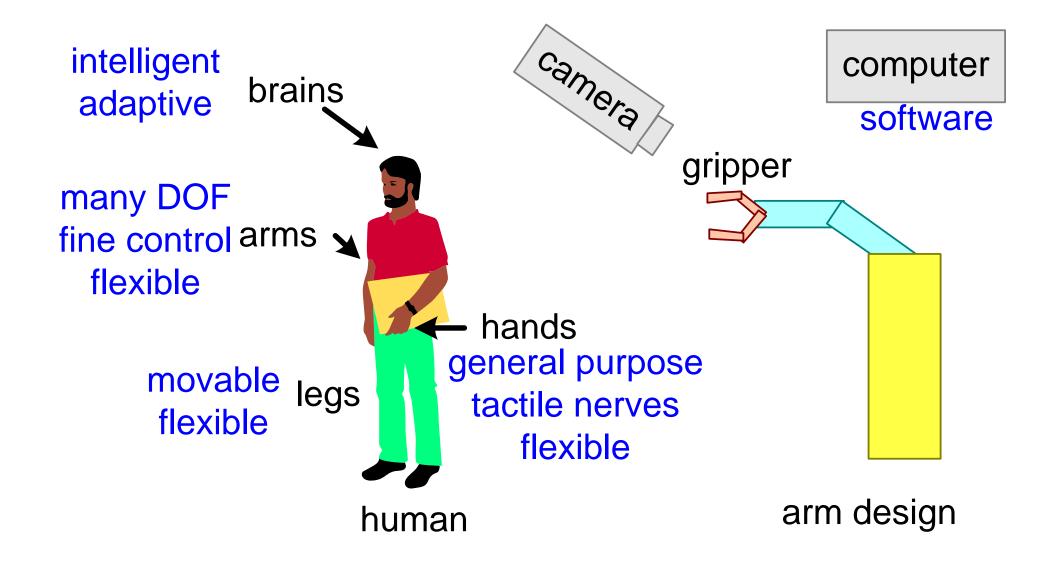
Stock travels along many workstations?

What are the critical design choices?

What concepts are available?



From Human to Robot





Robot Design Questions

What Gripper and Robot Concepts are appropriate?

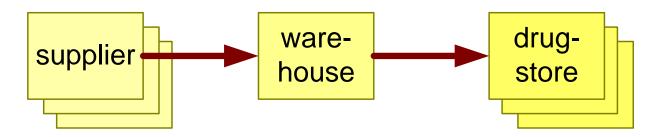
What are the desired properties?

What kind of items must be handled, and how?

→ Use examples to explore

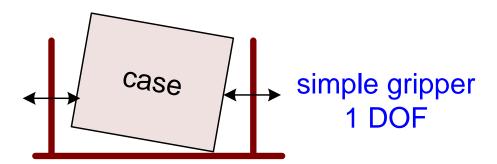


Example 1: Large Volume Drugstore



Large quantities box-like packages

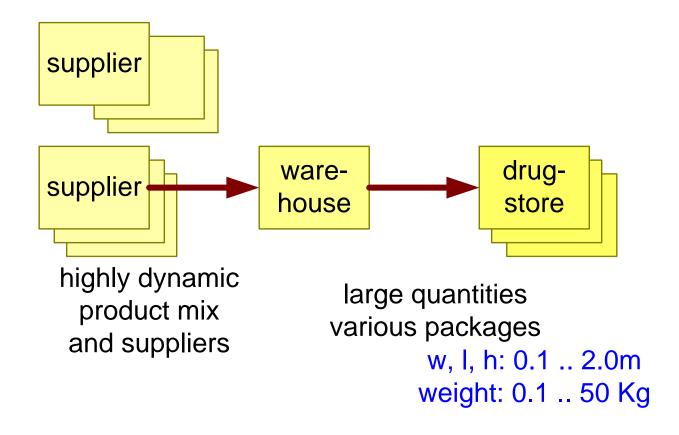
w, I, h: 0.1..0.5m weight: 1..40 Kg



simple robot
"H" for X, Y, and Z
movements



Example 2: High Dynamics

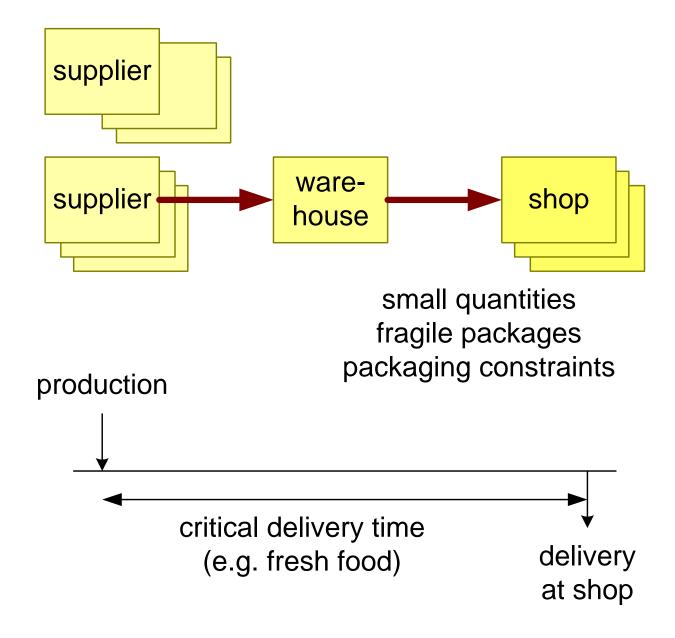


multiple grippers needed?

there is no time to teach (program) the robots how to handle package variety

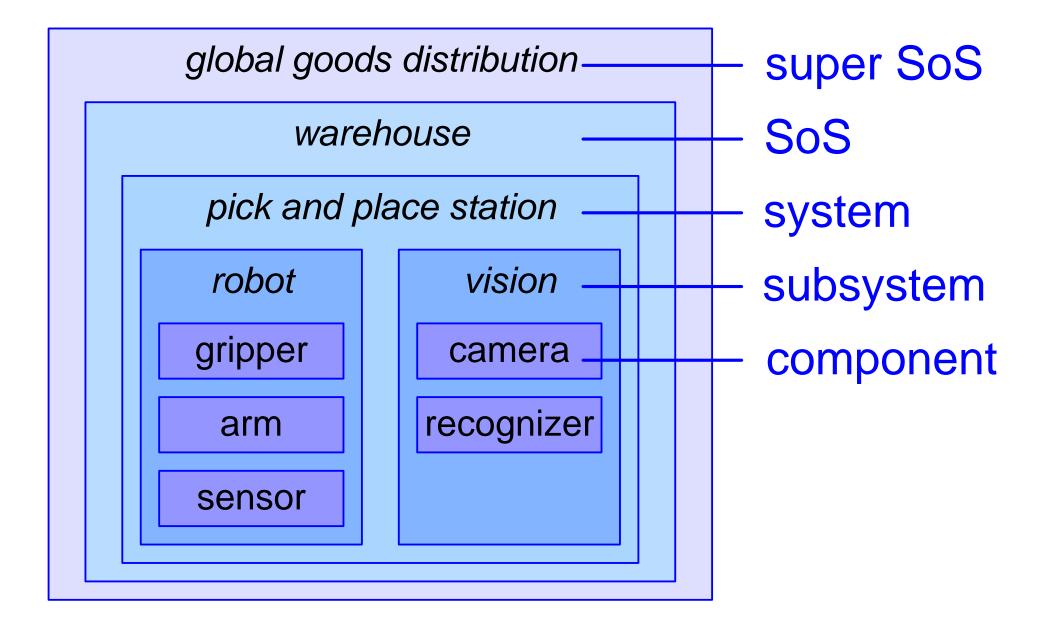


And more variants...



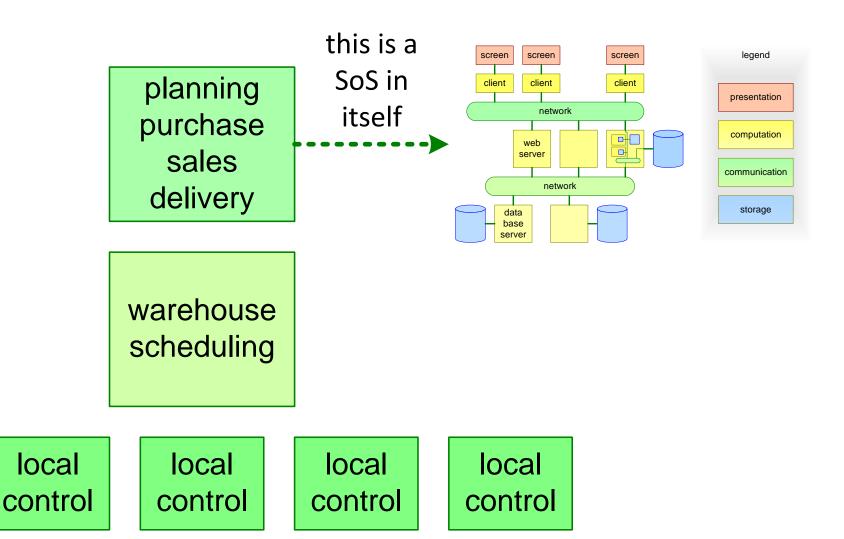


Recap: Levels and Partitioning





Warehouse Control





local

control





Typical Project Life Cycle

