### Module 33, Architectural Reasoning Design Fundamentals

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### **Abstract**

This module discusses fundamental design methods and techniques, especially partitioning, interface, behavior, and quantified performance design.

#### Distribution

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# System Partitioning Fundamentals

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### **Abstract**

The fundamental concepts and approach system partitioning are explained. We look at physical decomposition and functional decomposition in relation to supply chain, lifecycle support, project management, and system specification and design.

#### Distribution

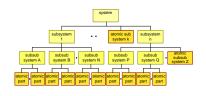
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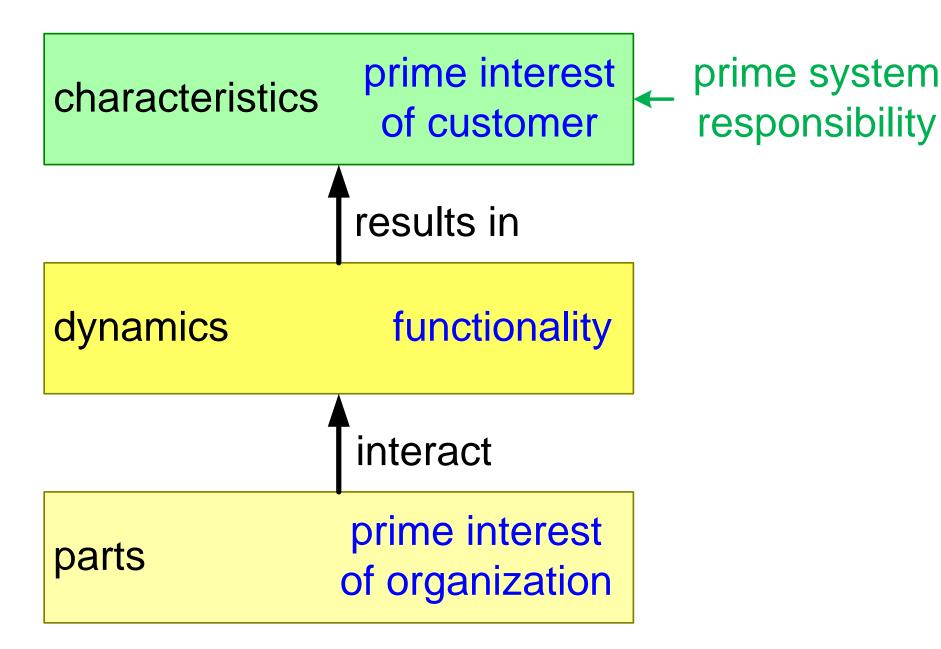
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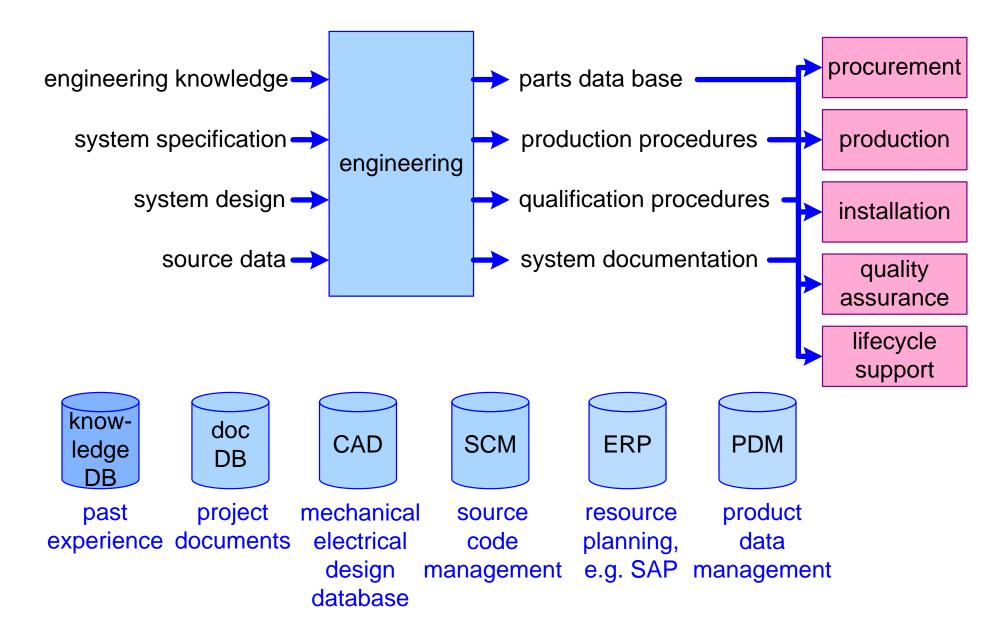


### Parts, Dynamics, Characteristics



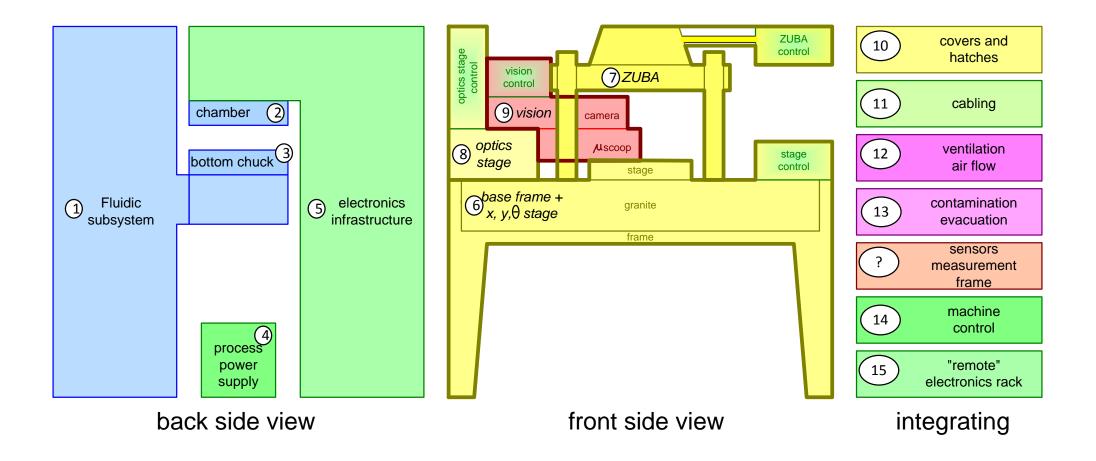


### Engineering



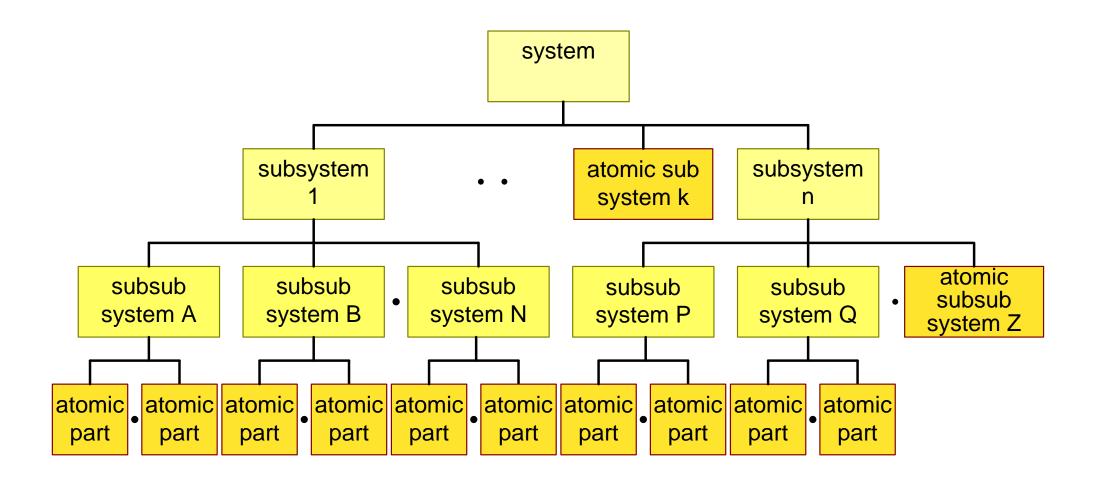


### **Example Physical Decomposition**



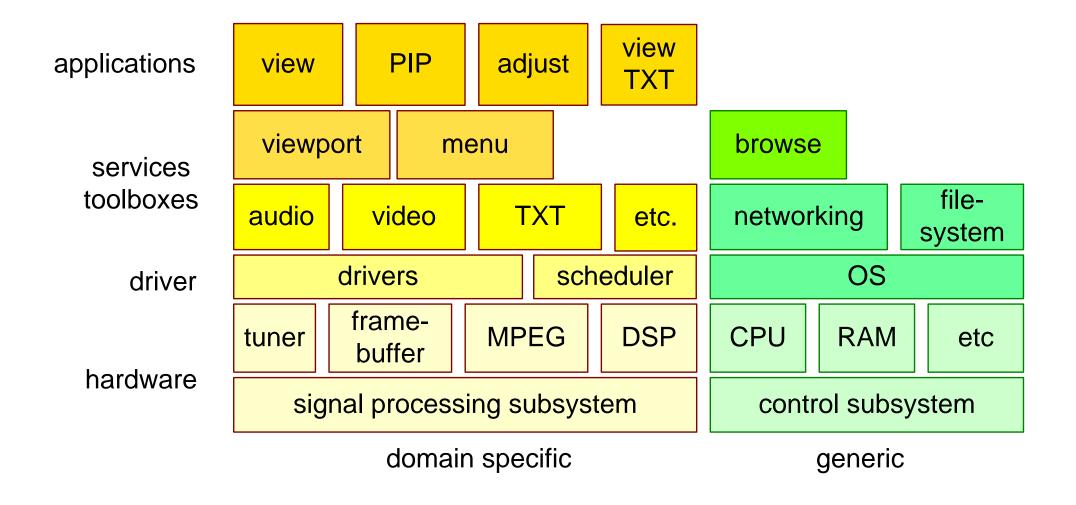


### Partitioning is Applied Recursively





# Software plus Hardware Decomposition





# Guidelines for Partitioning

the part is cohesive

functionality and technology belongs together

the coupling with other parts is minimal minimize interfaces

the part is selfsustained for production and qualification can be in conflict with cost or space requirements

clear ownership of part

e.g. one department or supplier



### How much self-sustained?

control SW

application SW

**HMI SW** 

control electronics

control interface

cooling

**EMC** shielding

main function qualification support

adjustment support

power stabilization

power conversion

power distribution production support

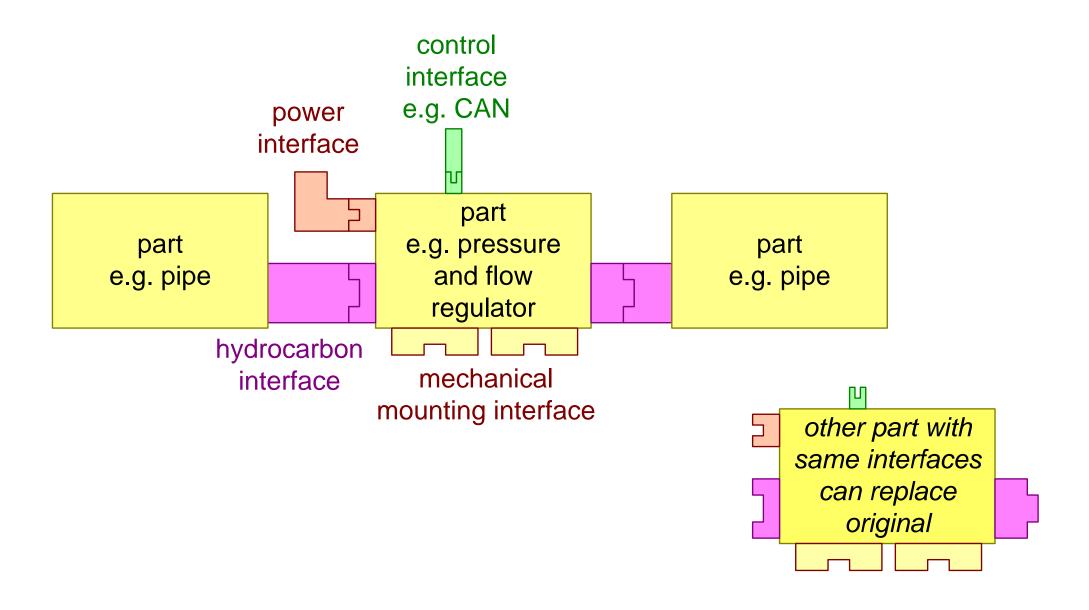
mechanical package

How self sustained should a part be? trade-off:

cost/speed/space optimization

logistics/lifecycle/production flexibility clarity

# Decoupling via Interfaces





# The Ideal Modularity

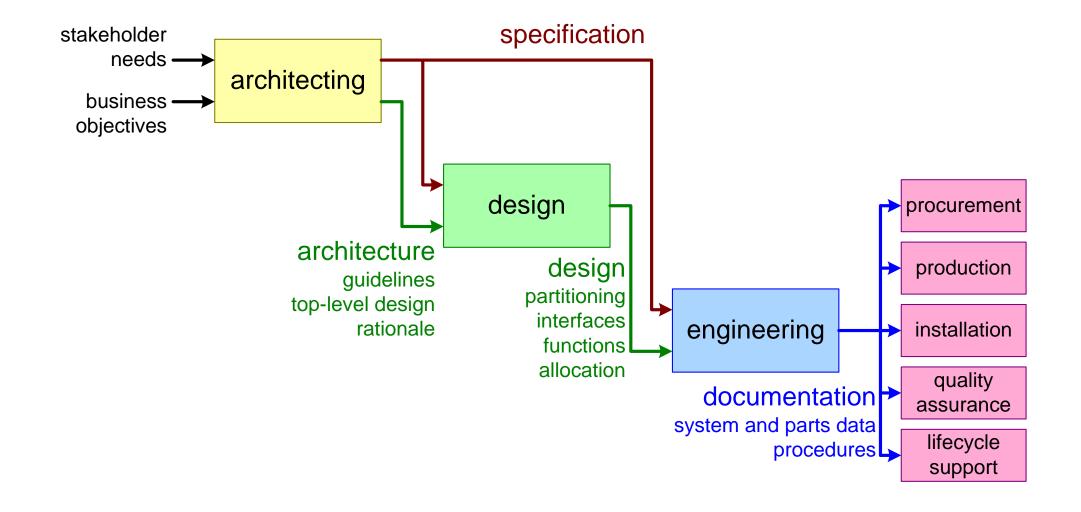
System is composed

by using standard interfaces

limited catalogue of variants (e.g. cost performance points)

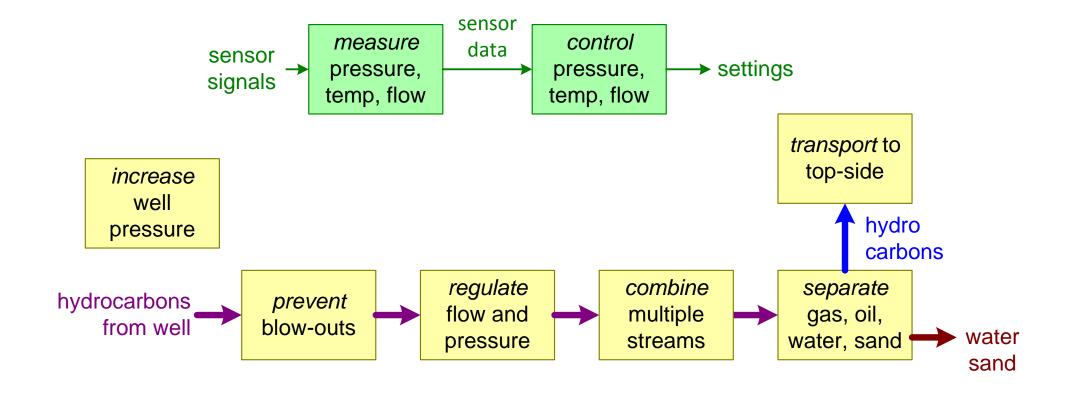


# **System Creation**





### Simplistic Functional SubSea Example





### **Functional Decomposition**

How does the system work and operate? Functions describe what rather than how. Functions are verbs. Input-Process-Output paradigm. Multiple kinds of flows: physical (e.g. hydrocarbons) information (e.g. measurements) control At lower level one part ~= one function pump pumps, compressor compresses, controller controls At higher level functions are complex interplay of physical parts e.g. regulating constant flow, pressure and temperature



### Quantification

Size	2.4m *	0.7m	* 1.3m
0.20			

Weight 1450 Kg

Cost 30000 NoK

Reliability MTBF 4000 hr

Throughput 3000 l/hr

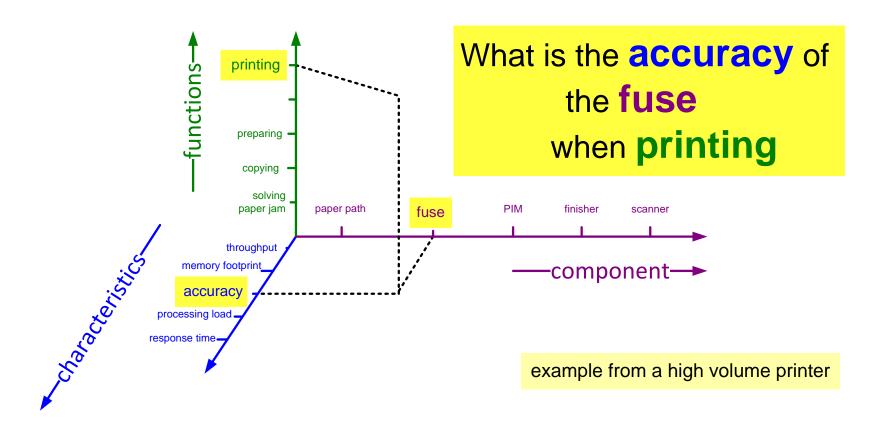
Response time 0.1 s

Accuracy +/- 0.1%

many characteristics of a system, function or part can be quantified

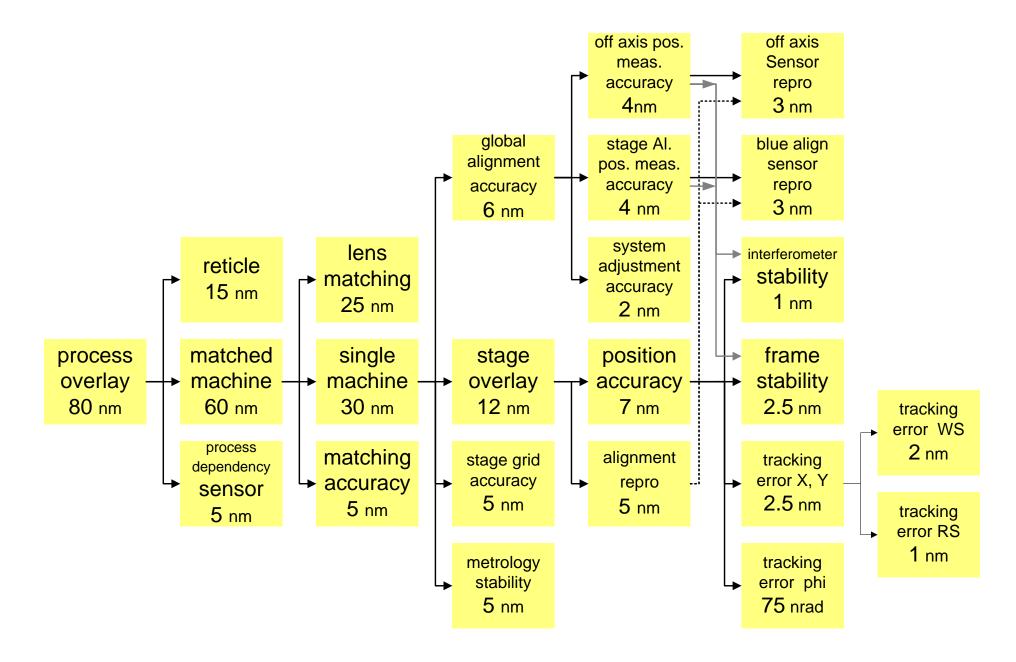
Note that quantities have a **unit** 

# How about the <characteristic> of the <component> when performing <function>?



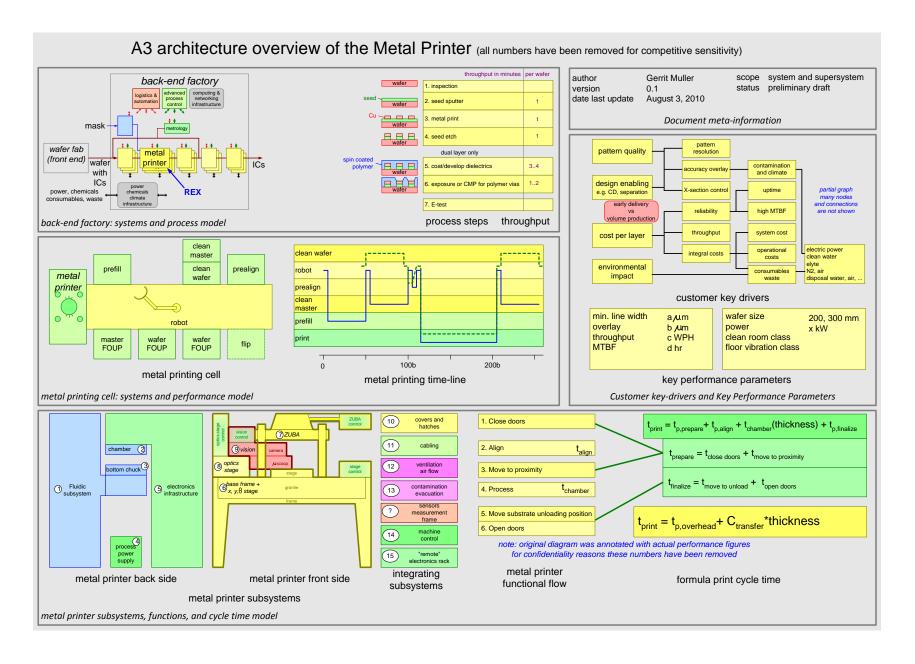


### Example Technical Budget





### Example of A3 overview





# Visualizing Dynamic Behavior

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### **Abstract**

Dynamic behavior manifests itself in many ways. Architects need multiple complementary visualizations to capture dynamic behavior effectively. Examples are capturing information, material, or energy flow, state, time, interaction, or communication.

#### Distribution

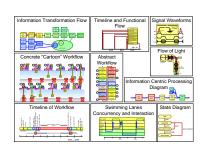
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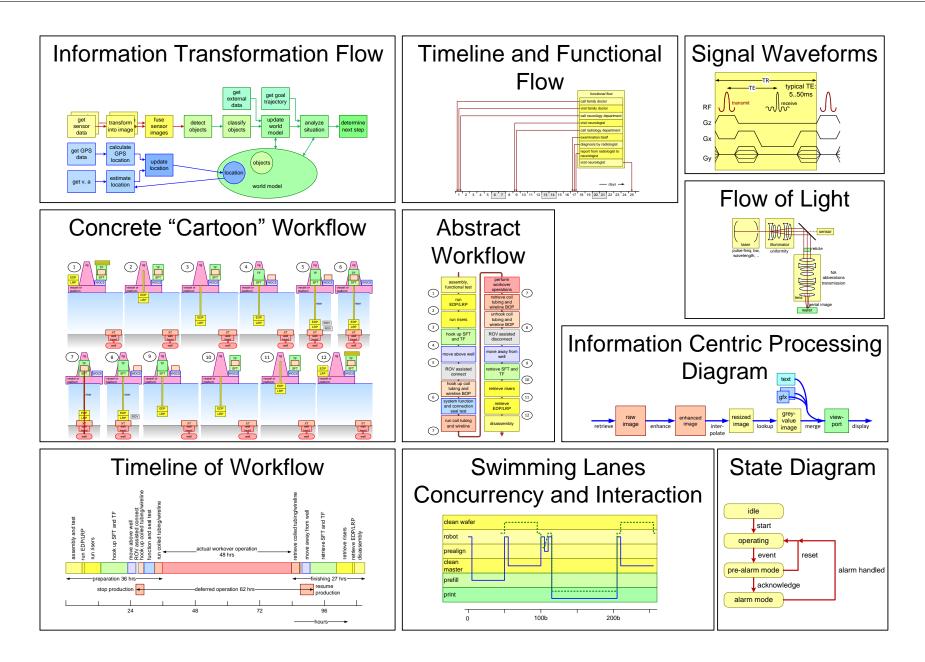
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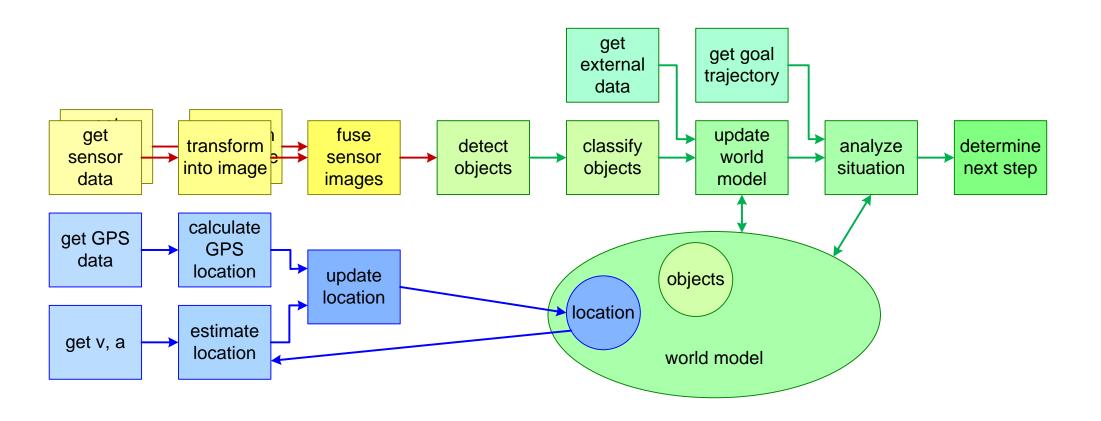
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### Overview of Visualizations of Dynamic Behavior

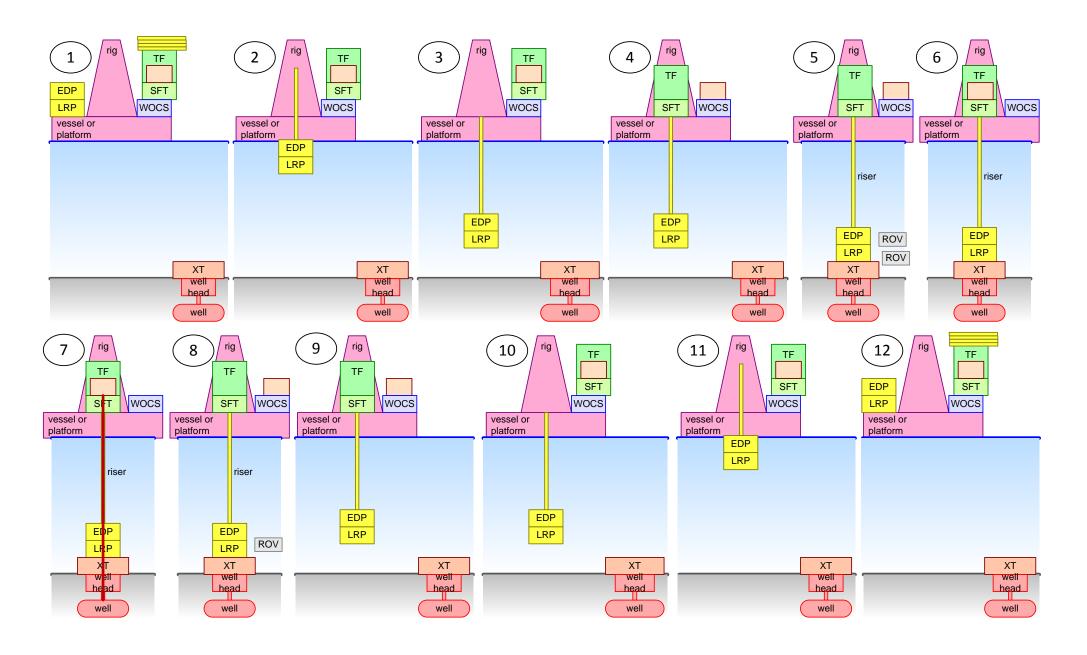


# Example Functional Model of Information Flow



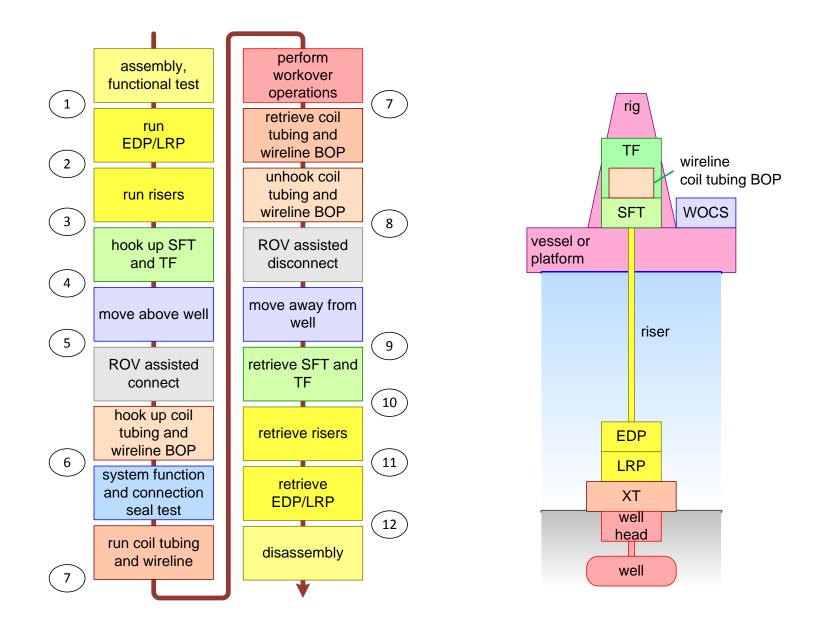


### "Cartoon" Workflow



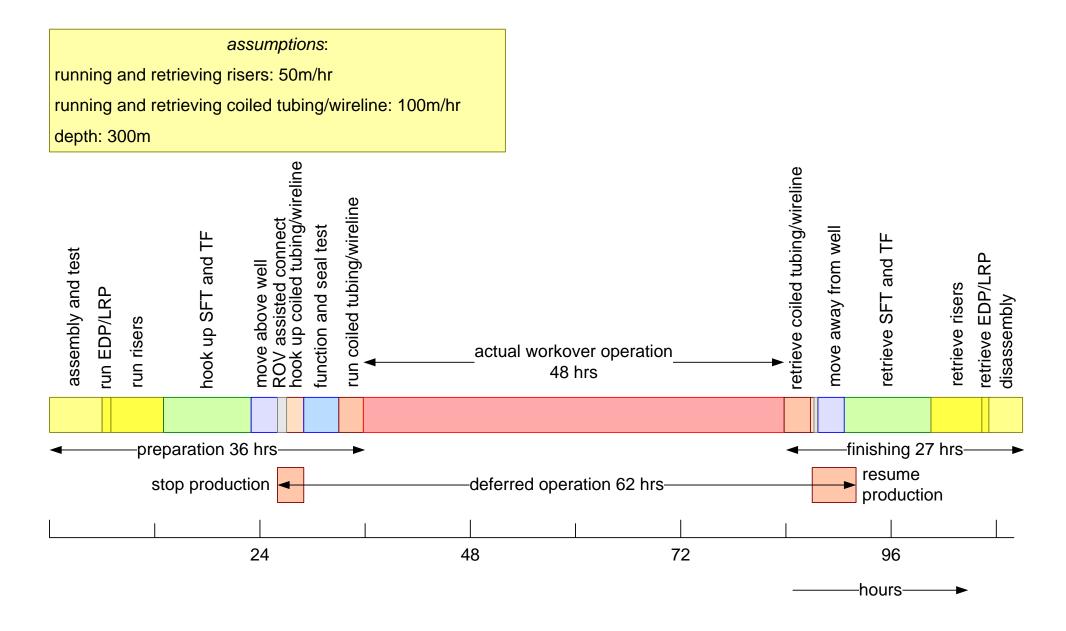


### Workflow as Functional Model



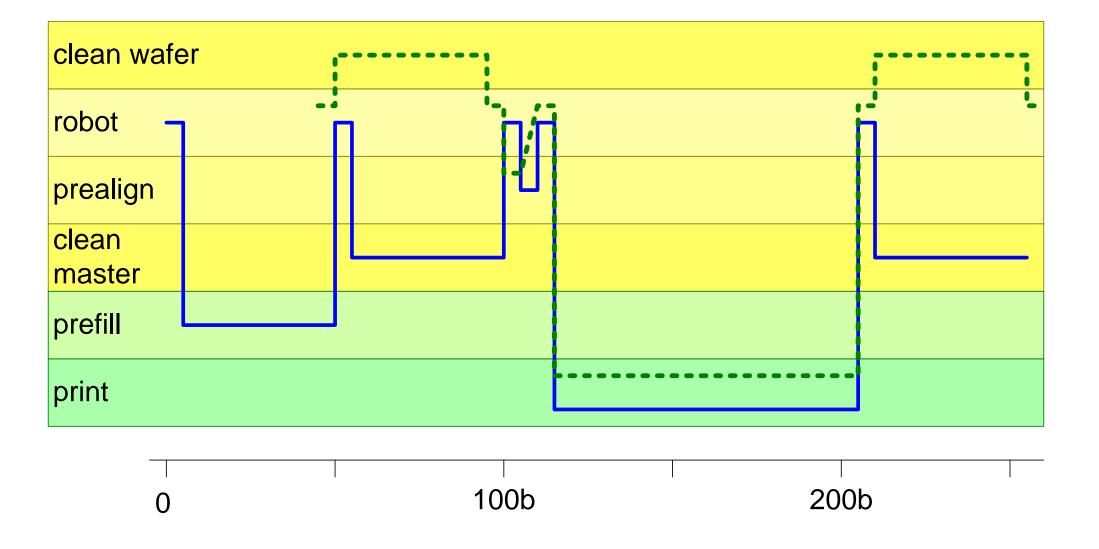


### Workflow as Timeline



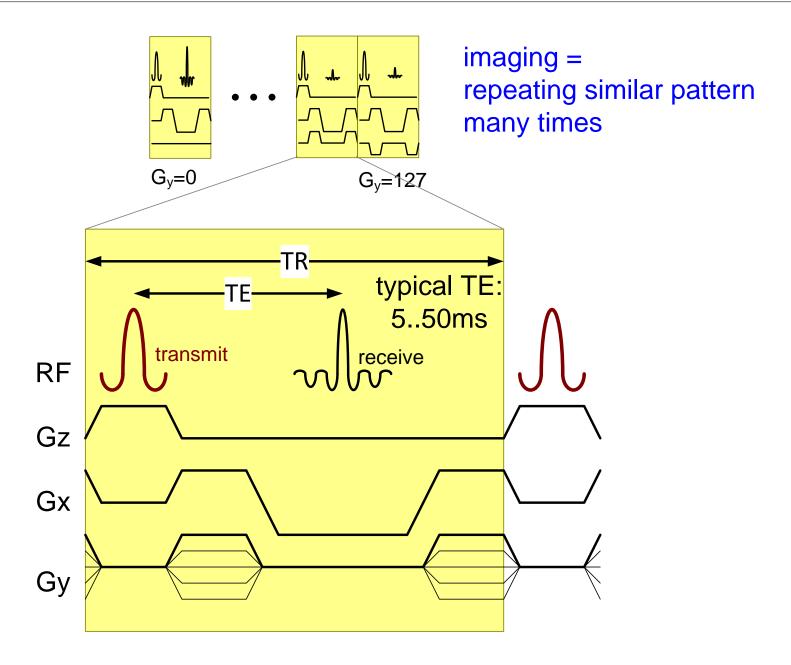


# Swimming Lane Example



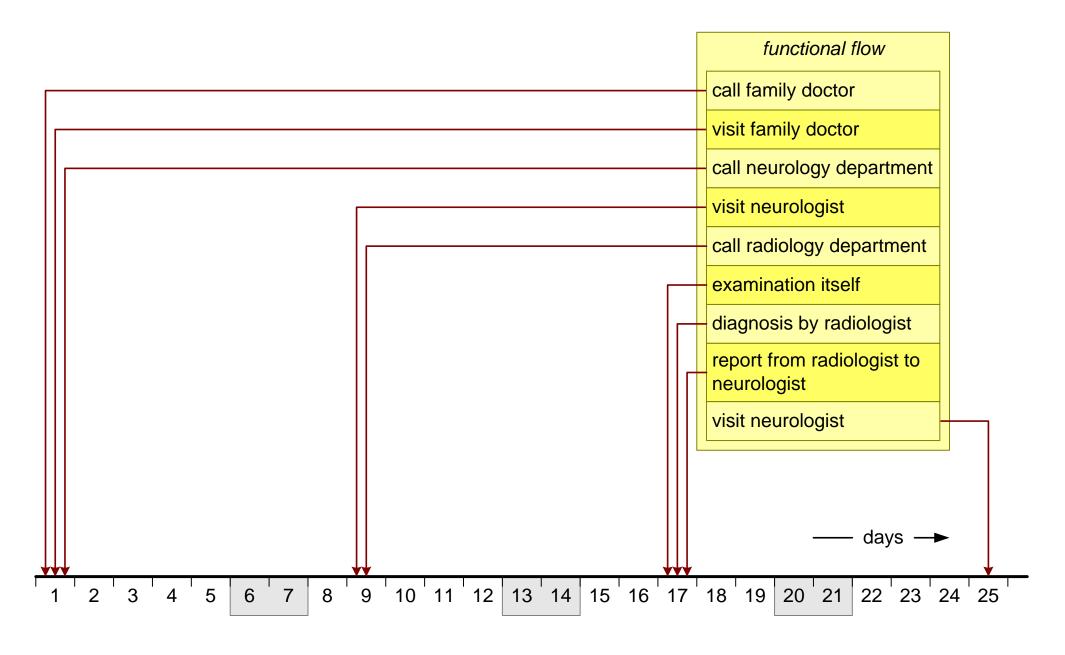


# **Example Signal Waveforms**



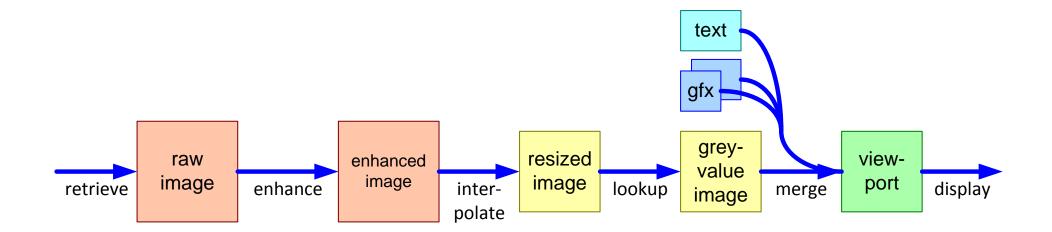


### Example Time Line with Functional Model



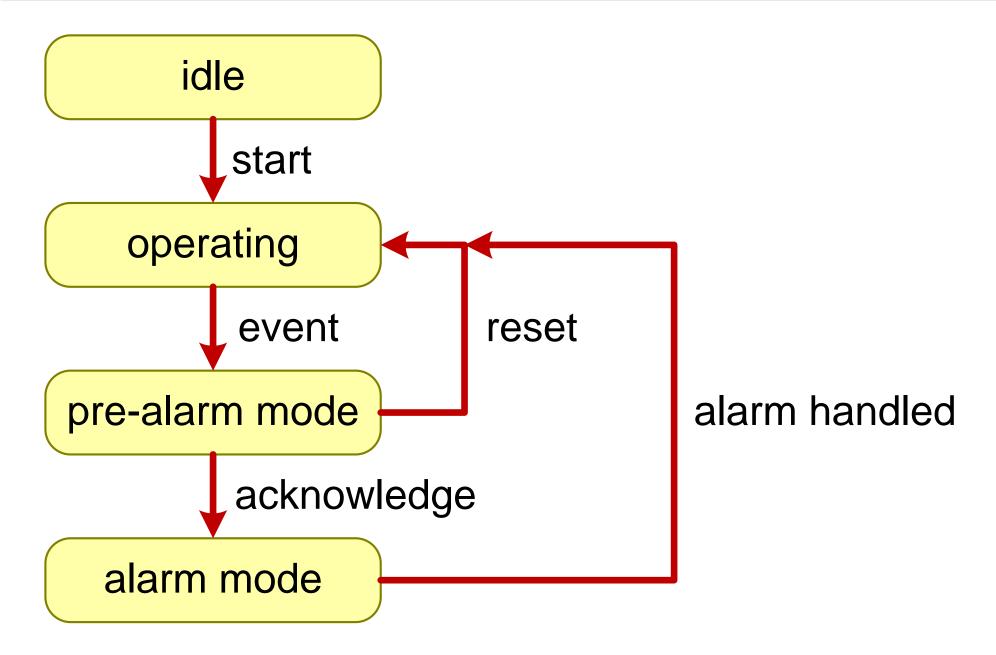


# Information Centric Processing Diagram



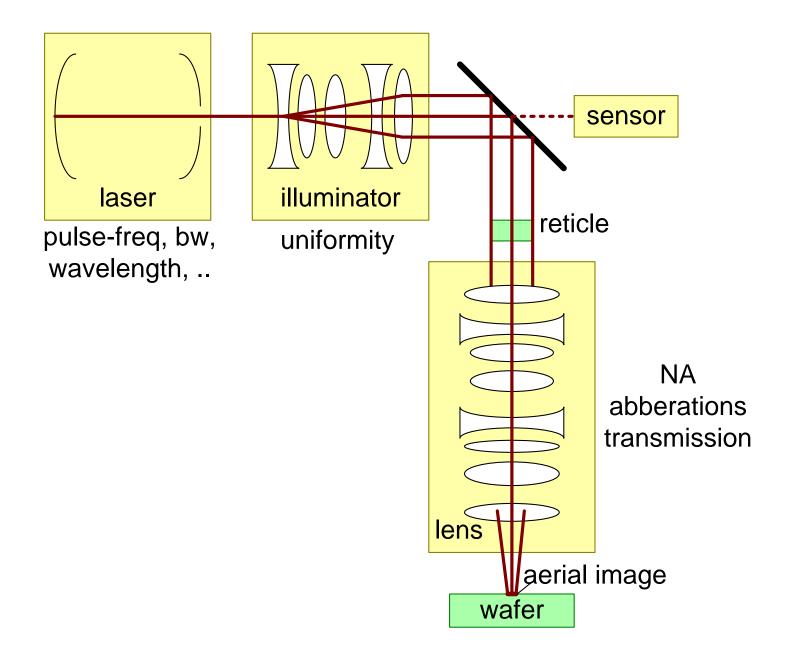


### **Example State Diagram**





# Flow of Light (Physics)





### Dynamic Behavior is Multi-Dimensional

How does the system work and operate?

Functions describe what rather than how.

Functions are verbs.

Input-Process-Output paradigm.

Multiple kinds of flows:

physical (e.g. hydrocarbons, goods, energy)

information (e.g. measurements, signals)

control

Time, events, cause and effect

Concurrency, synchronization, communication

multi-dimensional information and dynamic behavior



### **Exercise Dynamic Behavior**

Capture the **dynamic behavior** of the **internals** of your system in **multiple** diagrams.

Diagrams that capture dynamic behavior are among others:

- Functional flow (of control or information, material or goods, or energy)
- Activity or sequence diagrams (e.g. with "swimming lanes")
- State diagrams



### Exercise Block Diagram

Make a set of **block diagrams** capturing the **static parts** and **interfaces**.

Ensure coverage of the entire system, e.g. including service, training, production, etc.

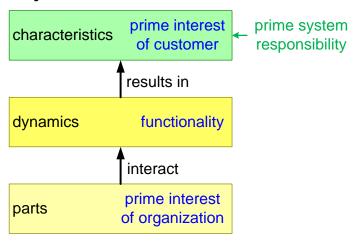
Show both **hardware** and **software** 

Good block diagrams have in the order of 10 to 20 blocks

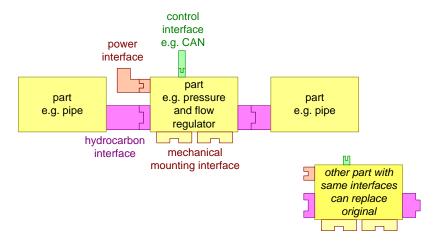


### Design Fundamentals

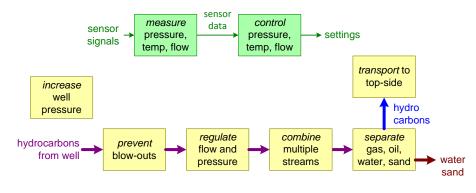
### Parts, Dynamics, Characteristics



### Decoupling via Interfaces



### **Dynamic Behavior**



### **Question Generator**

How about the **<characteristic>**of the **<component>**when performing **<function>**?

