From Sensor to System; Sensor Architecting

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Abstract

Researchers of sensors, typically focus on a set of critical characteristics of the sensors. However, do we know what is critical from a broader perspective, such as a device builder, a subsystem builder, the system, or the user of the system?

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Figure of Contents[™]



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The System: a Metal Printer



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Application of the System





Where will your Sensor be used?

ndicate the equivalent levels for your sensor or actuator				
sensor	imaging sensor			
device	camera			
component	optics chain			
subsystem	alignment			
system	printer			
application	metal printing			

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Worksheet: Note 3..5 KPPs for your Sensor

sensor				
imaging sensor				
device				
camera				
component				
optics chain				
subsystem				
alignment				
system				
printer				



The Subsysem: Alignment



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Basics of Alignment Function



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The Sensor







What are the 3 to 5 Key Performance Parameters of the sensor?

What are the 3 to 5 Key Performance Parameters of your sensor?

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Potential KPPs Sensor

Possible

Key Performance Parameters of the sensor

- spatial resolution
- contrast resolution
- frame rate
- image acquisition time
- image uniformity
- sensor size
- energy consumption
- cost price
- color range
- sensitivity



The Camera





Camera Block Diagram





What are the 3 to 5 Key Performance Parameters of the camera?

What are the 3 to 5 *Key Performance Parameters* of the device incorporating your sensor?

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Potential KPPs Camera

Possible

Key Performance Parameters of the camera

- image quality (resolution, uniformity, color range)
- acquisition performance (frame rate, acquisition time)
- camera size, weight
- camera energy consumption, thermal stability
- camera cost price
- storage capacity
- compression rate and quality
- communication performance



The Optics Chain



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What are the 3 to 5 Key Performance Parameters of the optics chain?

What are the 3 to 5 *Key Performance Parameters* of the component incorporating your sensor?

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Potential KPPs Optics Chain

Possible

Key Performance Parameters

of the optics chain

- position and angle stability
- wafer-to-sensor image quality (resolution, uniformity, color range)
- vertical size
- acquisition performance (frame rate, acquisition time)
- stage performance (speed, stability, reproducability)
- focus performance
- x, y range
- thermal stability
- cost, weight, size stage+optics



The Alignment Subsystem



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Alignment Workflow

1	move to marker position	
2	focus	
3	search markers	may result in new move and focus
4	determine dx, dy	
5	calculate master displacement	based on calibration data
6	move master	
7	search markers	may result in new focus
8	verify dx, dy	repeat steps 58 if needed



Alignment Algorithm



x, y accuracy may be higher than optical resolution

What are the 3 to 5 *Key Performance Parameters* of the alignment subsystem?

What are the 3 to 5 *Key Performance Parameters* of the subsystem incorporating your sensor?





Potential KPPs Alignment

Possible

Key Performance Parameters of the alignment subsystem

- dx, dy after alignment
- alignment cycle time
- robustness for markers, patterns, wafers, temperature
- cost, weight, size subsystem



The Printer System



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What are the 3 to 5 Key Performance Parameters of the printer system?

What are the 3 to 5 Key Performance Parameters of the system incorporating your sensor?

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Potential KPPs of the Printer

Possible

Key Performance Parameters of the printer system

- print quality (pattern resolution, cross section control)
- overlay (=positioning accuracy)
- throughput
- reliability (uptime, high MTBF)
- robustness for markers, patterns, wafers, temperature
- integral costs (system cost, operational costs)
- consumables and waste
- fab interoperability (wafers and information)
- footprint



The Context



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How Process can Influence Alignment



Context: process influence on alignment

what if little contrast

what if slow transition

what if wafer surface height varies

what if shadows



what if marker is damaged



Revisiting the Sensor





Part of the Design Space

	bene	fits	disadvantages					
high resolution	igh accurate dx, dy		long acq time long transfer time long calculation time high energy consumption					
large FoV	easy to find markers		long acq time long transfer time high energy consumption					
red light	visibility marker		low optical resolution					
blue light	high optical resolution		poor visibility marker					
continuous on	thermal steady state		requires continuous cooling					
sensor	raw image	camera	compressed stream	alignment processor				
accuracy ↔ alignment time								



Sensor Architecting





Sensor Architecting: 8 Orders Zoom in-out



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