

Bachelor Course Systems Engineering: Architectural Reasoning; Homework

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Abstract

This is the homework for a course for bachelor students in systems engineering for the part architectural reasoning

Distribution

This article or presentation is written as part of the Gaudí project. The Gaudí project philosophy is to improve by obtaining frequent feedback. Frequent feedback is pursued by an open creation process. This document is published as intermediate or nearly mature version to get feedback. Further distribution is allowed as long as the document remains complete and unchanged.

January 25, 2024
status: draft
version: 1.10

Specify and design

a full-electric

TukTuk

(versatile, urban, no emission)



http://en.wikipedia.org/wiki/Auto_rickshaw#/media/File:DKoehl_colombo_auto_rickshaw.JPG
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Schedule

Thursday January 25, 10:00 lecture, 11-15 class work

Monday January 29, 10:00 lecture, 11-15 class work

Friday February 9, submit homework 1

Monday February 12, 10:00 lecture, 11-15 class work

Thursday February 15, 10:00 lecture, 11-15 class work

Thursday February 29, submit presentation of homework 2

Tuesday April 3, submit individual reflection report of homework 2

Case during this course

Specify and design

an **Intelligent Pest Control Robot**.

Climate change will cause the migration of many animals that are disease carriers, e.g. ticks, mosquitos, bats. The goal is to mitigate health risks. You may determine your own scope, such as clients,

location, and application

e.g., Kongsberg
Viken
Norway
Europe

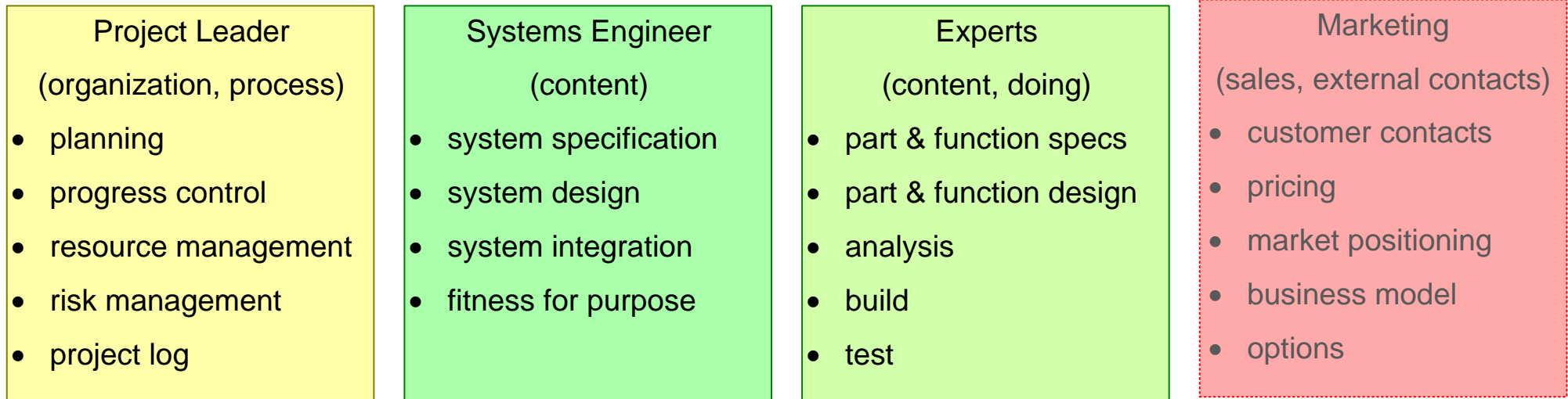
e.g., mosquito control,
rat control

e.g., civilians,
government agencies,
pest control companies,
municipalities

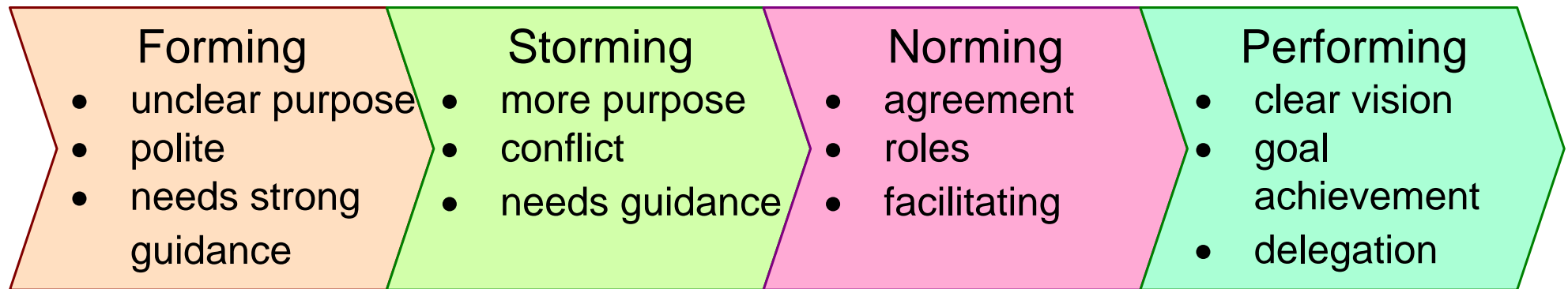
Company: start-up

- Each group is a **start-up company**; you are its **management team**
- You have **investors** that are **funding** you in the first phase
- At the **end of the spring**, the investors will decide on further funding
- You have to build a **presentation** with a **proposal** for the next phase, such that you **convince the investors** to fund the next phase

Allocate your roles



Be Aware of the Team Dynamics



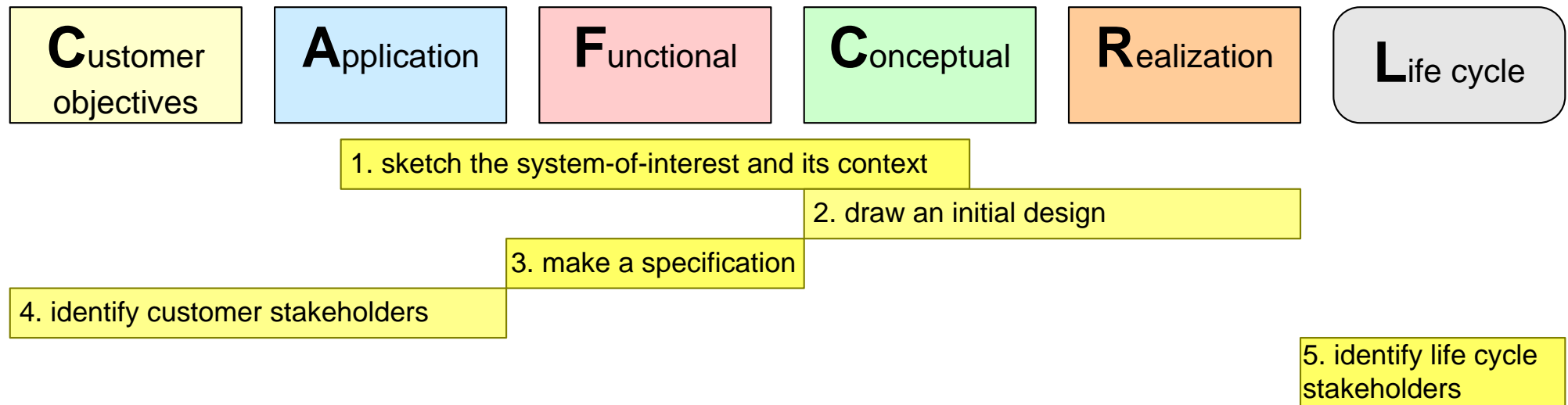
after <http://www.mspguide.org/tool/tuckman-forming-norming-storming-performing>

Class-work Day 1: Exploration

Use **time-boxes** of **15 minutes** and perform the following steps:

- **Sketch** the **system-of-interest** and its immediate **context**
 - Annotate the sketch (e.g. main components, interfaces, functions, ...)
- Draw an **initial design**
- Make a **specification** of the system-of-interest (view it as a blackbox)
 - What functionality, performance, interfaces, standards or regulations
- Identify the main **customer stakeholders** and their **concerns**
- Identify the main **life cycle stakeholders** and their **concerns**
- Review and make a plan to consolidate in a presentation

Class-work Day 1 mapped on CAFCR



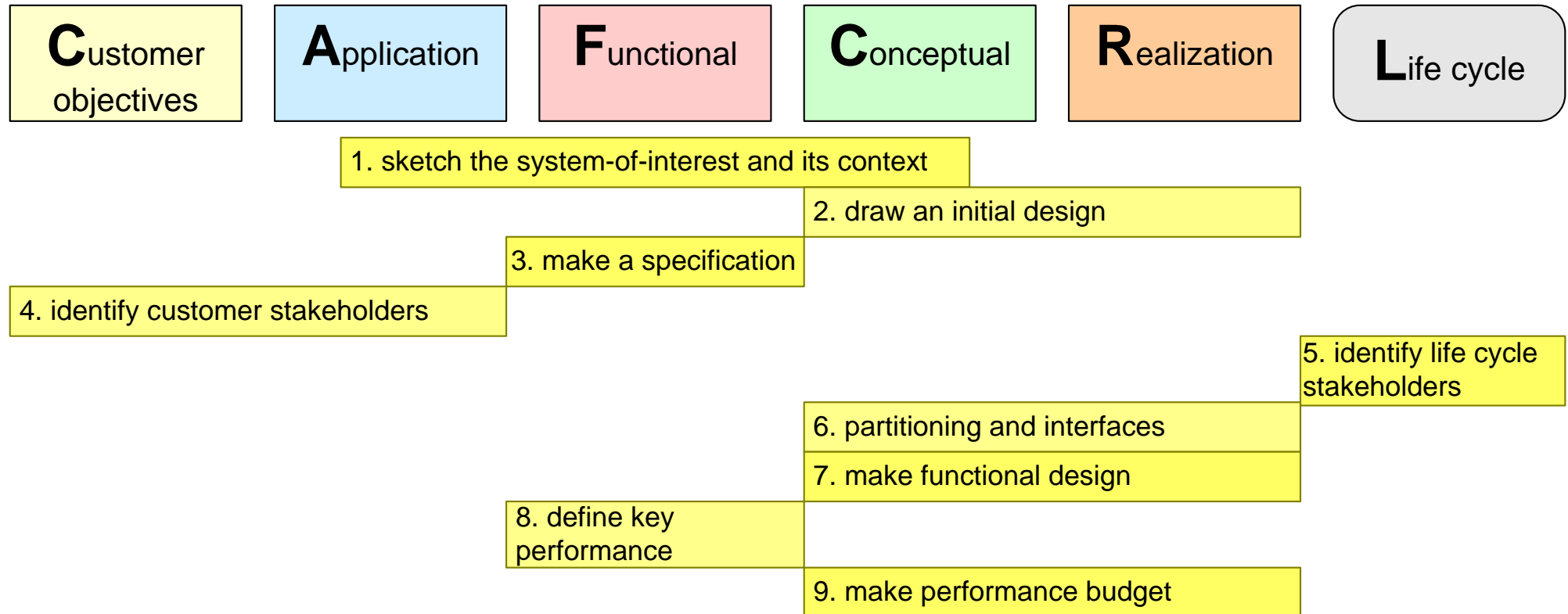
Class-work Day 2: Elaboration

Start second iteration by elaborating FCR views

Use time-boxes of about 30 minutes

- Decompose the system in subsystems, decompose one subsystem in subsubsystems.
- Show the subsystems and interfaces in a block diagram
- Make a functional model of the internals of the system-of-interest
 - Use one or more diagrams to show the dynamic behavior
- Define 5..10 Key Performance Parameters of the system-of-interest
 - Define a use case to support the definition of KPPs
- Make a technical budget for one of the key performance parameters
- Review and make a plan to consolidate in a presentation

Class-work Day 2 mapped on CAFCR



Homework after Day 2

Transform your results in electronic form (e.g., PowerPoint or Visio)

Develop two alternative solutions/concepts

Compare the three solutions using a Pugh matrix

- define 5..10 criteria for comparison

- score the solutions on a scale from 1 (poor) to 5 (very good)

- recommend a solution with a rationale

Make a list of questions triggered by the first iteration

Search for facts to ease the next class-work

Submit as draft presentation via Canvas

Home work instructions

Homework instructions

presentation

filename: BSEAR team<your teamnumber/name> homework<number>

e.g. BSEAR team1 homework1.ppt

all team members on front page

upload homework to Canvas

Questions email to: <gerrit . muller@ gmail . com>

from/cc: <all email addresses of team members>

Class-work Day 3: Elaboration CA-views

Continue second iteration by elaborating CA views

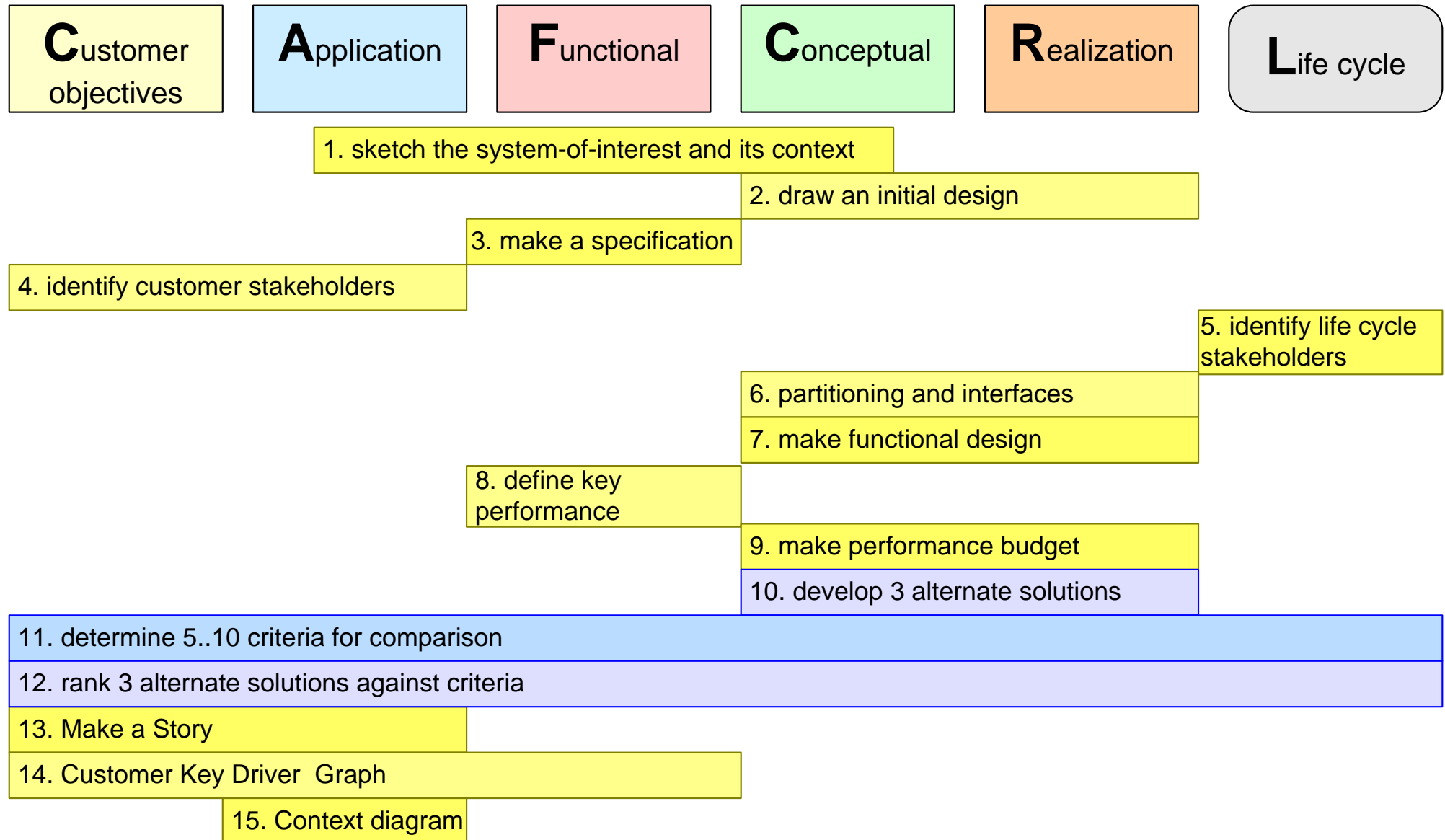
Use time-boxes of about 40 minutes

- Develop a story that helps you to understand the customer better and that facilitates analysis of specification and design
 - Verify your story against the story criteria
- Develop a customer key driver graph
 - Start with Key Performance Parameters and ask “why (is this needed)” repeatedly.

Use time-box of about 20 minutes for the remaining task

- Make a context diagram

Class-work Day 3 mapped on CAFCR



Class-work Day 4: Elaboration Life Cycle

Continue second iteration by elaborating life cycle view

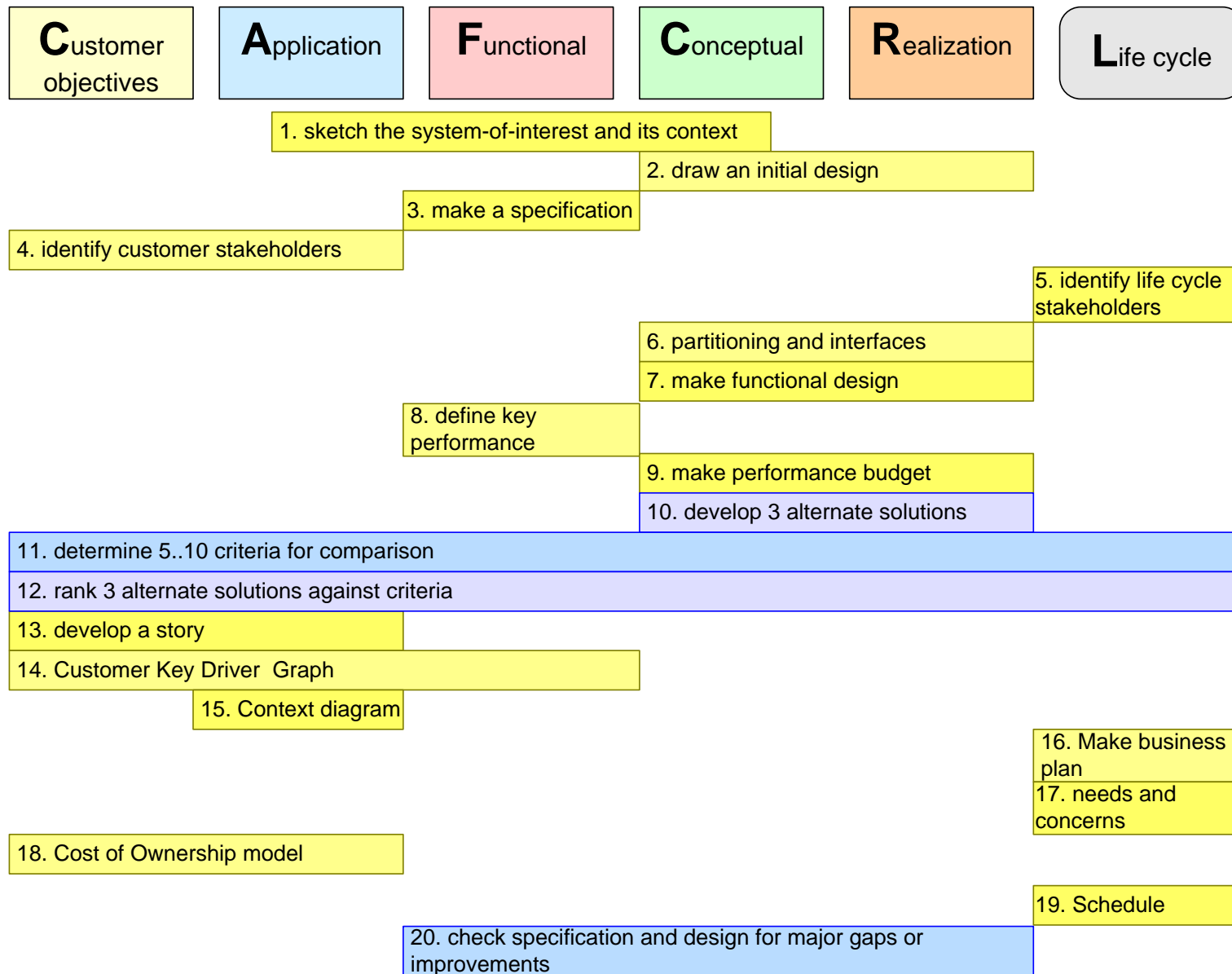
Use time-boxes of about 30 minutes

- Develop a business plan for your company
 - determine your role in the value chain
 - determine income, expenses, and investments
 - estimate cash flow as function of time
- Identify needs and concerns from life cycle stakeholders
 - determine life cycle key drivers and key performance parameters
- Make a Cost of ownership estimate for customers

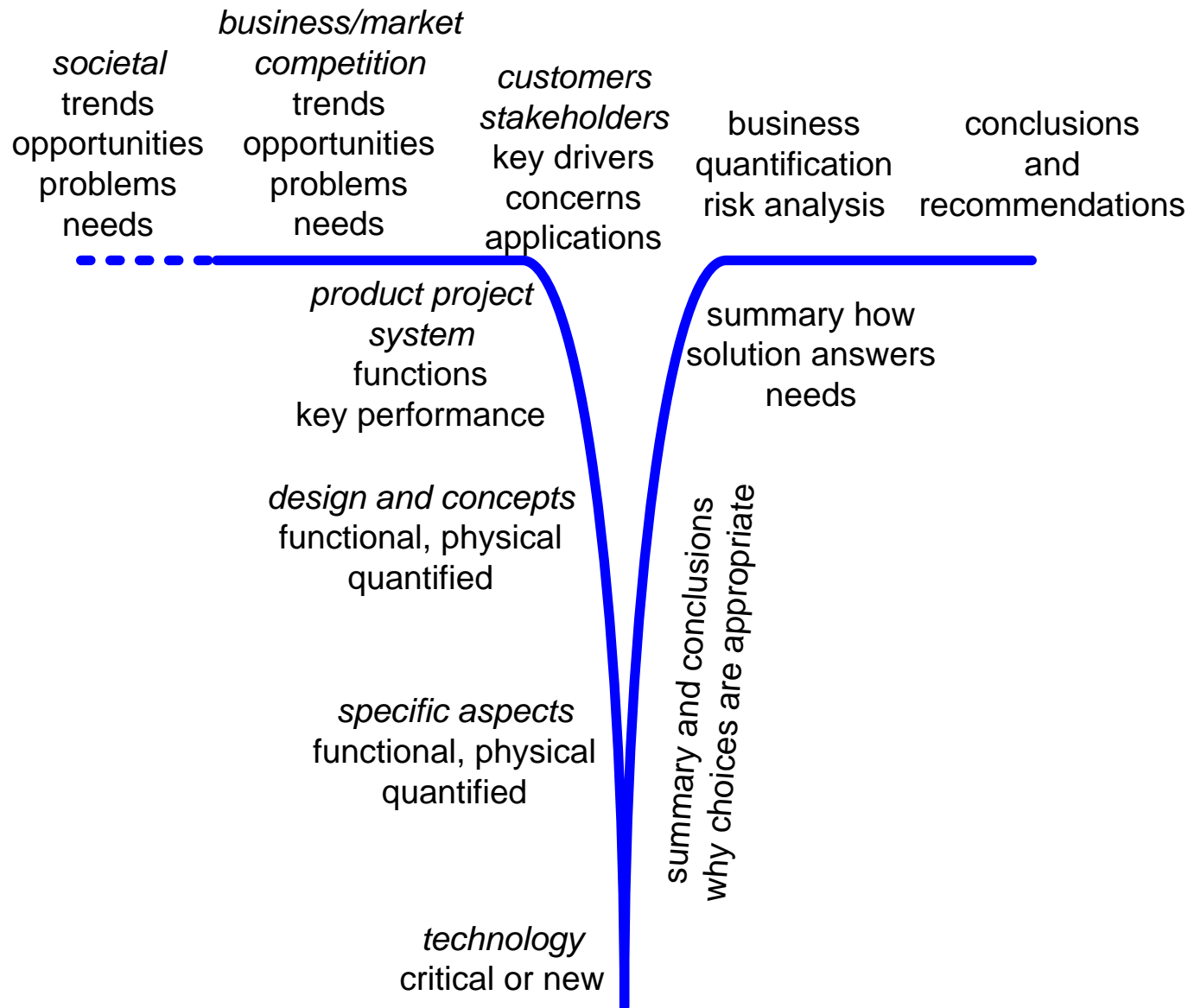
Use time-box of about 20 minutes for the remaining task

- Make a schedule for development and start of deployment

Class-work Day 4 mapped on CAFCR



T-shaped Presentation



Homework after Day 4

Check specification and design for major gaps or improvements

Transform your results in electronic form (e.g., PowerPoint or Visio)

Make a T-shaped presentation for your management, covering all 4 days; its main purpose is to make an initial go/no-go decision

Submit this presentation via Canvas

Write an individual reflection report, max 2 A4s:

What are your main learning points?

What aspects deserve most attention in next phase of your project? Explain why.

Submit this individual reflection report via Canvas

Specify and design

a **Drone Interception System**.

The goal is to prevent drone misuse, e.g. paparazzi's, terrorist attacks, etc.

You may determine your own scope, such as clients,

e.g., celebrities,
festivals, oil companies

location, and application

e.g., Kongsberg

Viken

Norway

Europe

e.g., security

counterintelligence

Specify and design

a **Smart Covid Test Collecting and Handling System.**

The goal is to achieve good and actual insight in infections.

You may determine your own scope, such as clients,

e.g., children,
employees,
or elderly

location, and application

e.g., Kongsberg
Viken
Norway
Europe

e.g., screening
diagnosis
monitoring
tracing

Specify and design

a **Smart Waste System**.

The goal is to achieve sustainability, where resources are fully recycled.

You may determine your own scope, such as type of waste,

e.g., plastic
metals

location, and application

e.g., Kongsberg
Viken
Norway
Europe

e.g., residential
industrial
agricultural

Specify and design

a Smart and Sustainable, e.g. energy neutral etc., House or Building for Norway,

which will be comfortable, attractive and affordable

Case previous course

Specify and design

an autonomous waste collector.

This collector finds and removes waste from the environment.

Specify and design

an autonomous track/road maintainer for elderly Norwegians.

This robotic vehicle, amongs others, keeps the drive to their home fully operational (in winter).

Specify and design an
Unmanned Humanitarian Response/Support Vehicle,

which will be able to reach locations with
poor, bad, or destroyed access.

Specify and design
a full-electric
TukTuk
(versatile, urban, no emission)



http://en.wikipedia.org/wiki/Auto_rickshaw#mediaviewer/File:DKoehl_colombo_auto_rickshaw.JPG
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Specify and design
a full-electric
drive-by-wire
race kart



photo <http://nl.wikipedia.org/wiki/Bestand:Outdoor-karting.jpg>